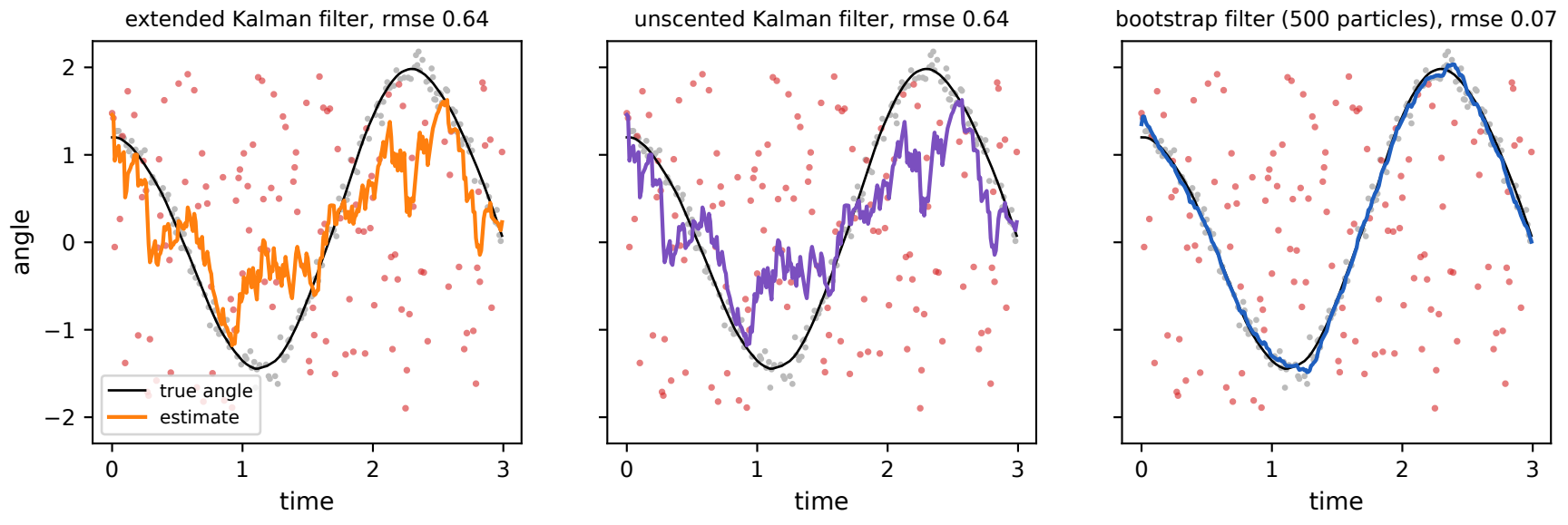

extended Kalman filter, rmse 0.64
unscented Kalman filter, rmse 0.64
bootstrap filter (500 particles), rmse 0.07
angle
time
true angle
estimate