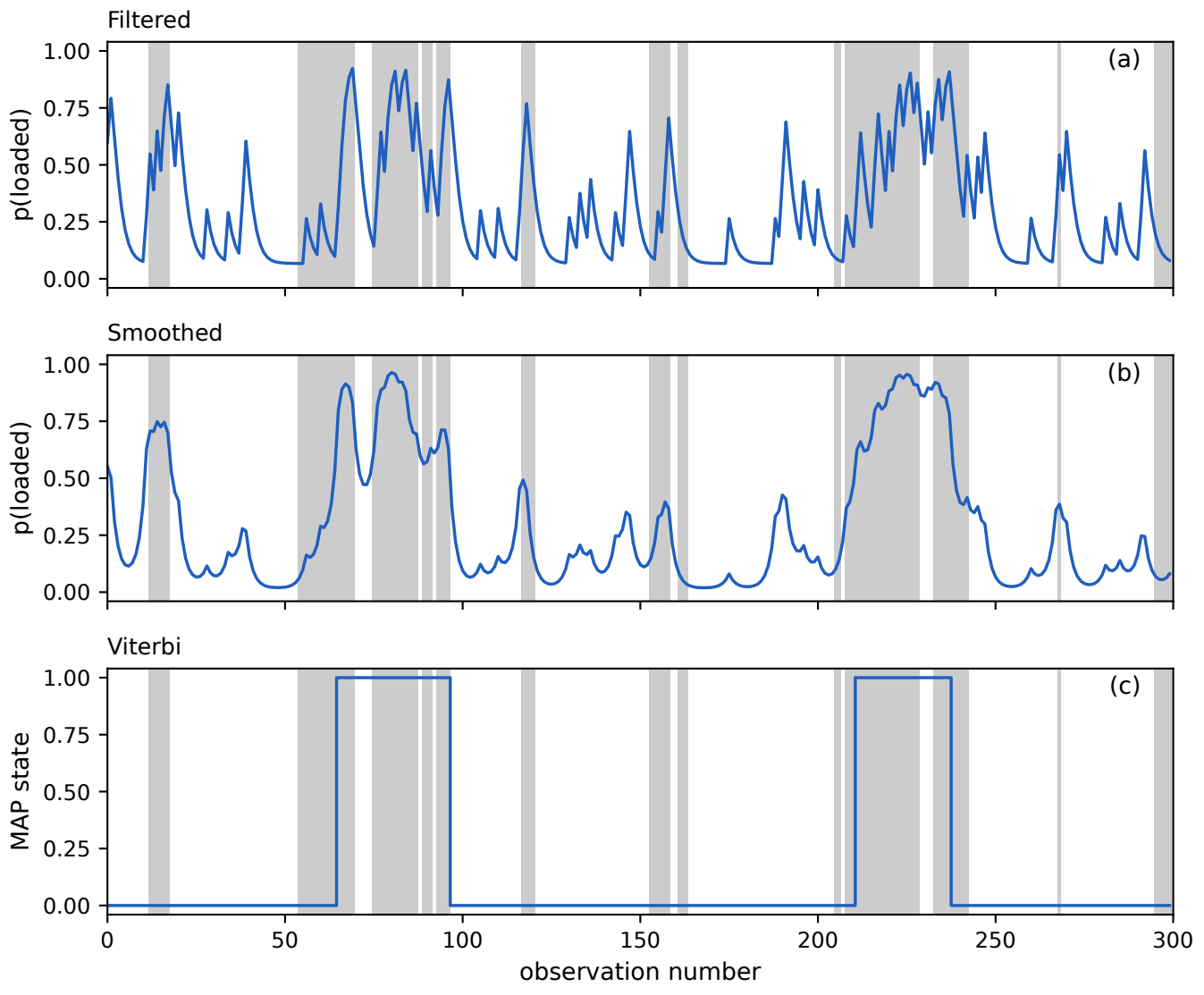

Filtered
(a)
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0.75
0.50
0.25
0.00
Smoothed
(b)
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0.75
0.50
0.25
0.00
Viterbi
(c)
MAP state
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
250
300
observation number