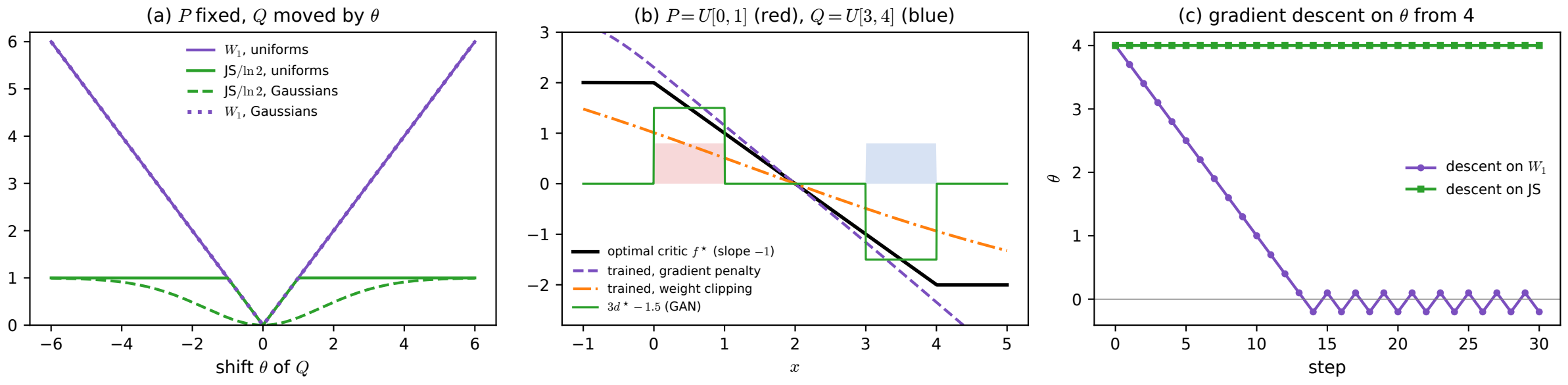

(a) P fixed, Q moved by θ
W_1, uniforms
JS/ln 2, uniforms
JS/ln 2, Gaussians
W_1, Gaussians
shift θ of Q
(b) $P = U[0,1]$ (red), $Q = U[3,4]$ (blue)
optimal critic $f^\star$ (slope -1)
trained, gradient penalty
trained, weight clipping
$3d^\star - 1.5$ (GAN)
x
(c) gradient descent on θ from 4
descent on W_1
descent on JS
θ
step