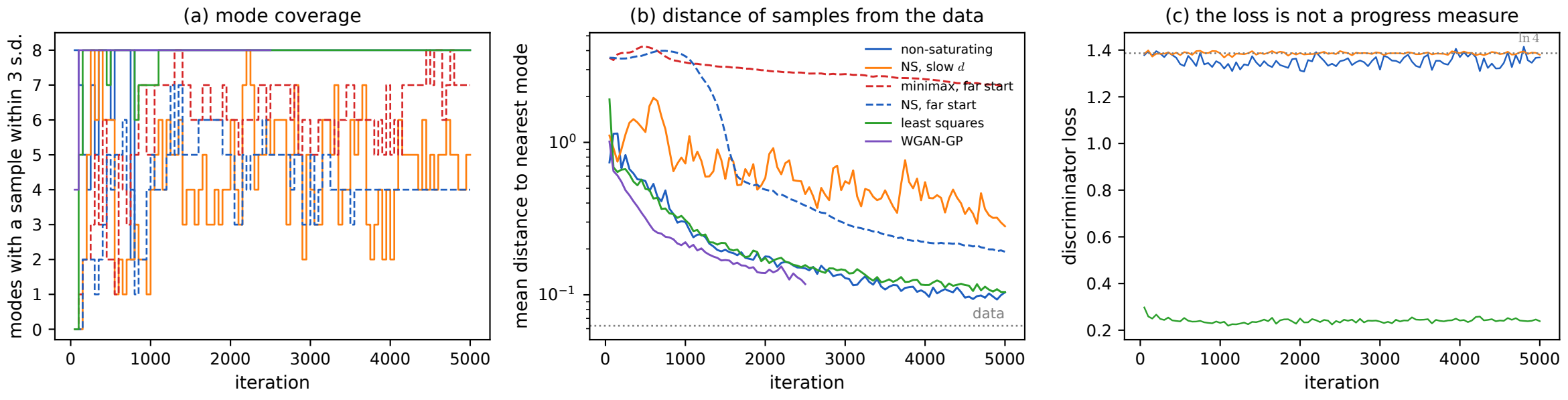

(a) mode coverage
modes with a sample within 3 s.d.
iteration
(b) distance of samples from the data
mean distance to nearest mode
non-saturating
NS, slow d
minimax, far start
NS, far start
least squares
WGAN-GP
data
iteration
(c) the loss is not a progress measure
discriminator loss
ln 4
iteration