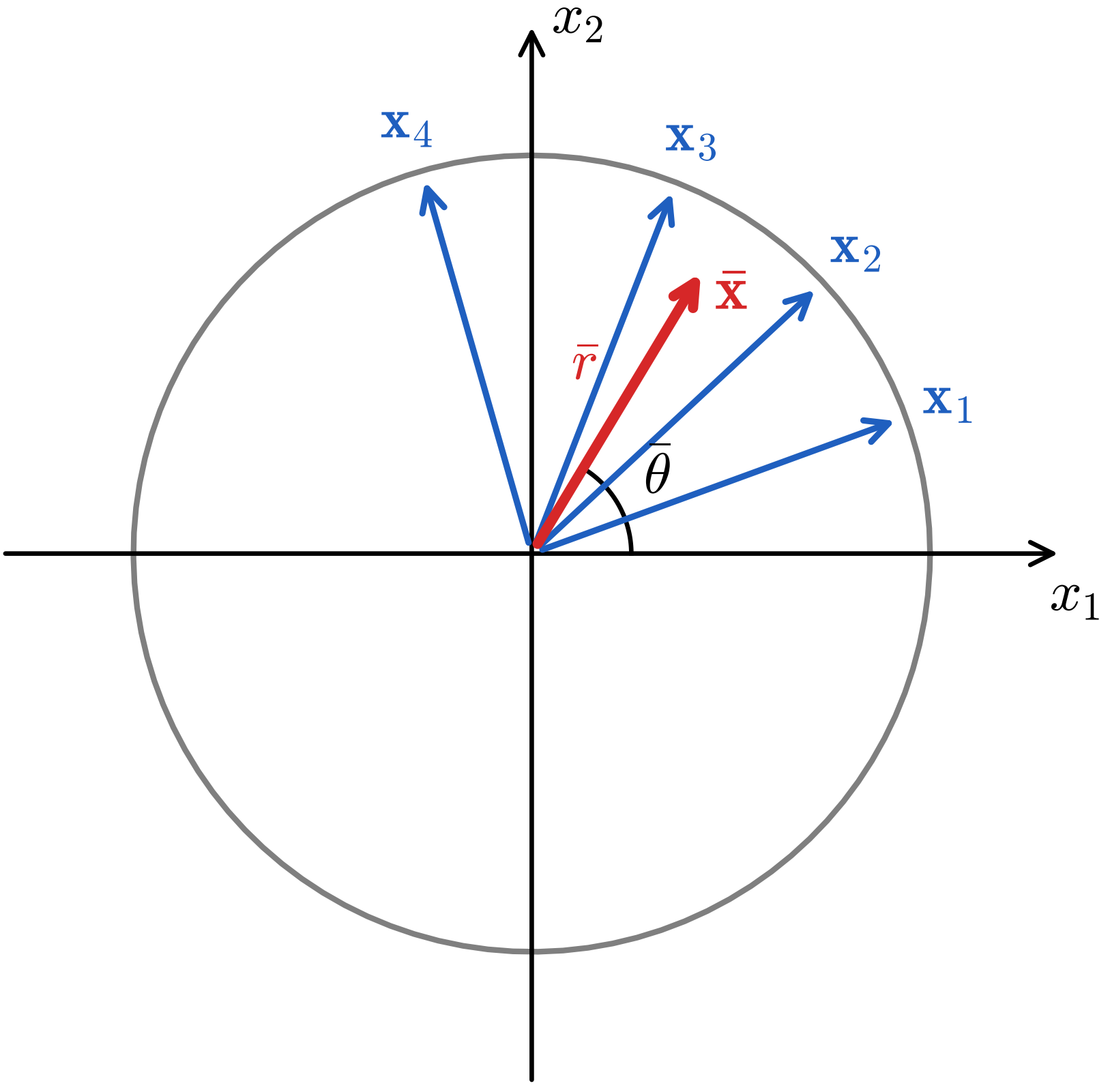

x_2
$\mathbf{x}_4$
$\mathbf{x}_3$
$\mathbf{x}_2$
$\bar{\mathbf{x}}$
$\bar{r}$
$\mathbf{x}_1$
$\bar{\theta}$
x_1